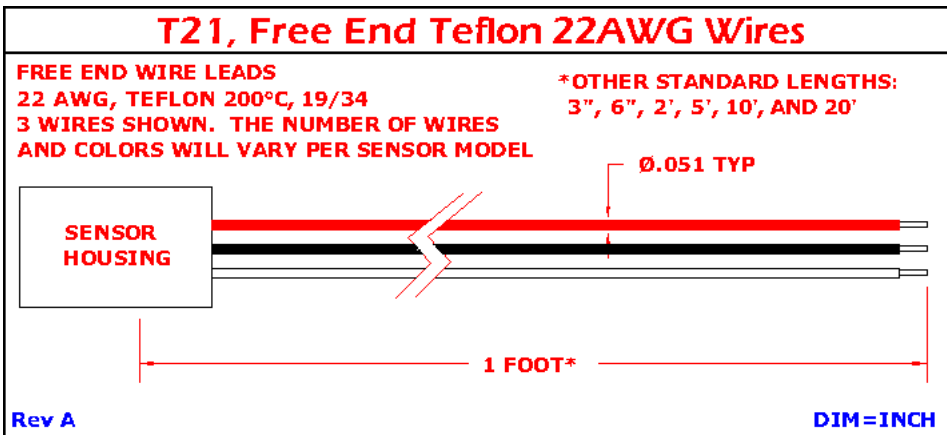
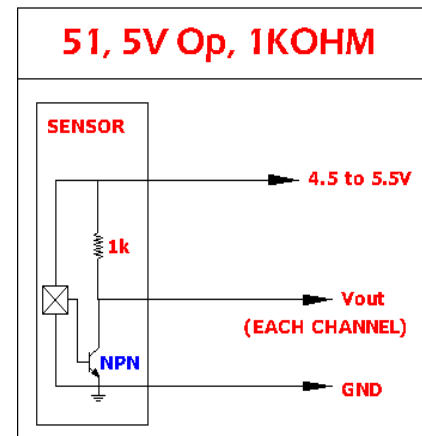
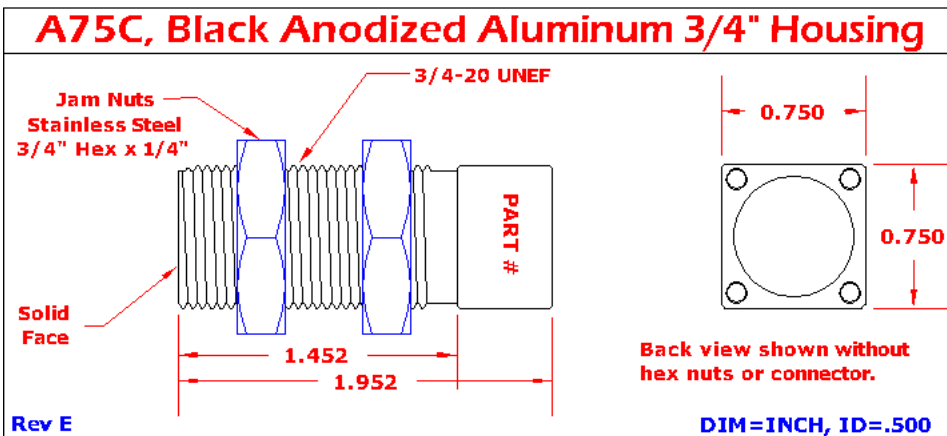


- o SELF CALIBRATING
- o BEST CHOICE FOR STEEL GEARS LESS THAN 4 PITCH
- o 1/2 TOOTH MIN. HYSTERESIS

| ENVIRONMENTAL SPECIFICATIONS - A75C | |
|-------------------------------------|---------------------------------|
| Corrosion Resistance | 500 hours salt spray ASTM B-117 |
| Installation Torque | 64 Foot-Pounds Maximum |
| Enclosure | Nema 1,3,4,6, & IEC IP67 |
| Vibration | 10 G's 2 to 2000 Hz Sinusoidal |
| Mechanical Shock | 100 G's, 11 ms Half-Sine |



| Connections Chart | |
|--------------------|-----------|
| Red | Vcc |
| Black | Ground |
| White | Speed |
| Green | Direction |
| T21-37ADSDO | |

| Date Code 'YYM' | | | |
|----------------------|-------|-------|-------|
| YY = YEAR, M = MONTH | | | |
| A JAN | D APR | H JUL | L OCT |
| B FEB | E MAY | J AUG | M NOV |
| C MAR | G JUN | K SEP | N DEC |

The 37ADSDO Digital Speed Sensor provides 2 digital outputs as gear teeth rotate by the sensor's face. These sensors have 2 internal sensing elements that are physically placed 1/4, 3/4 or 1 1/4 tooth apart. The internal quadrature phase angle (phase shift from channel A to channel B) ideally should be 90 degrees. This will only happen if the correct gear pitch is used, and the sensor is aligned to the target's rotation direction. Therefore, when ordering this sensor, it cannot be built until the factory receives the gear pitch for the intended target.

Gear pitch = (the # of teeth on the gear) / (the gear's contact diameter in inches)

Specifications may not be valid when the application is not detecting an end-sensed, 14.5 pressure angle, steel spur gear. The presence of ferrous metals or strong magnetic fields in close proximity to the sensor's internal magnet may also invalidate the specifications. Engineers are available to assist in target design and applications with non-standard targets. Custom target specifications can only be guaranteed when the customer supplies a target along with any additional components that may affect sensor output, and the customer has validated function in the finished application.

The 37ADSDO is a self calibrating sensor with dynamic peak detection, making it the best choice for the detection of non-standard gears and targets such as bolt heads and holes in rotating discs. The direction signal is resolved by a D Flip flop. Internal signal B is used for the D signal, and signal A (SPEED) runs the clock input. When the gear changes direction, the direction signal changes states upon the falling edge from SPEED. The direction signal is designed to always power up with the output off if the target is not moving. Check our website or contact us to compare all of our speed and direction output gear tooth sensors.

*Sensor Solutions * V: (970) 879-9900 F: (970) 879-9700 * www.sensorso.com * Rev CEA*

37ADSDO-51, Electrical & Functional Specifications

| ABSOLUTE MAX LIMITS | MIN | MAX | UNITS |
|---------------------------|------|------|----------|
| Supply Voltage, Vcc | -.3 | 5.5 | Volts DC |
| Voltage applied to output | -0.3 | +5.5 | Volts |
| Current into output | -- | 20 | mA |
| Current out of output | -- | 5mA | mA |
| Load Dump, 40mS Rs=20 | -- | n/a | Volts |
| Output Power, T=25C | -- | 350 | mW |

| ELECTRICAL SPECS | CONDITIONS | MIN | MAX | UNITS |
|----------------------------|--------------------|-----|-------|----------|
| Temperature Range * | Operating | -40 | +110* | Deg C |
| Supply Voltage, Vcc | Over temperature | 4.5 | 5.5 | Volts DC |
| Supply Current, Output Off | Into Vcc | +10 | +26 | mA |
| Frequency Range ** | Near zero speed | 0.1 | 15k** | Hz |
| Vol, Low Level Vout | Vcc=5, Rload > 10k | 0 | 0.7 | Volts |
| Voh, High Level Vout | Rload > 10k | 4.5 | 5.25 | Volts |
| Pull up resistor | Internal | 1.9 | 2.1 | k ohms |
| Output Rise Time 10-90% | C < 100pF | -- | 1.0 | uS |
| Output Fall Time 90-10% | C < 100pF | -- | 1.0 | uS |
| ESD *** | Nondestructive | -- | 2000 | Volts |
| EMI *** | 20k to 1 GHz | -- | 20 | V/M |

* T max = 125°C is available, contact factory.

*** Similar product qualified.

** 20 kHz available, contact factory.

**** Non contacting

| TARGET PERFORMANCE GEAR PITCH ~(#Teeth/Diam. in inches) | AIR GAP RANGE**** | TYPICAL MAX GAP | TYP. OUTPUT DUTY CYCLE | ALIGNMENT SKEW ANGLE |
|--|-------------------|-----------------|------------------------|----------------------|
| 4 (.785" tooth to tooth) | .000 to .150" | .200" | 40 to 60 % | ±25 deg |
| 6 (.524" tooth to tooth) | .000 to .120" | .180" | 40 to 60 % | ±25 deg |
| 8 (.393" tooth to tooth) | .000 to .080" | .125" | 40 to 60 % | ±25 deg |
| 12 (.262" tooth to tooth) | .000 to .050" | .085" | 35 to 65 % | ±25 deg |
| 16 (.196" tooth to tooth) | .000 to .040" | .055" | 35 to 65 % | ±20 deg |
| 20 (.157" tooth to tooth) | .000 to .025" | .045" | 30 to 70 % | ±15 deg |
| 24 (.131" tooth to tooth) | .000 to .015" | .035" | 30 to 70 % | ±10 deg |

Rev C

CHARACTERISTIC-OPTION_GEAR PITCH MARKED ON THIS SURFACE, yy=OPTION, gp=GEAR PITCH (e.g. _08 = 8 PITCH GEAR)

DATE CODE, THIS SURFACE

DO NOT CONTACT FACE TO FACE

CONTACT WITH OTHER MAGNETS WILL REDUCE THE MAXIMUM OPERATING GAP

ALIGNED AS SHOWN, DIRECTION IS LOW FOR CW ROTATION

ALIGN ARROW PARALLEL TO GEAR ROTATION AS SHOWN

A75C-37ADSDO